

# Accuracy of a non-invasive mapping system for the localisation of re-entrant VT site of origin and its relationship to myocardial scar on cross-sectional imaging.

Jaffar Al-Sheikhli, Tarek Mahdy, Rafaella Siang, Ian Patchett, Leann Marshall, Jamal Khan, Tarv Dhanjal.

## Introduction

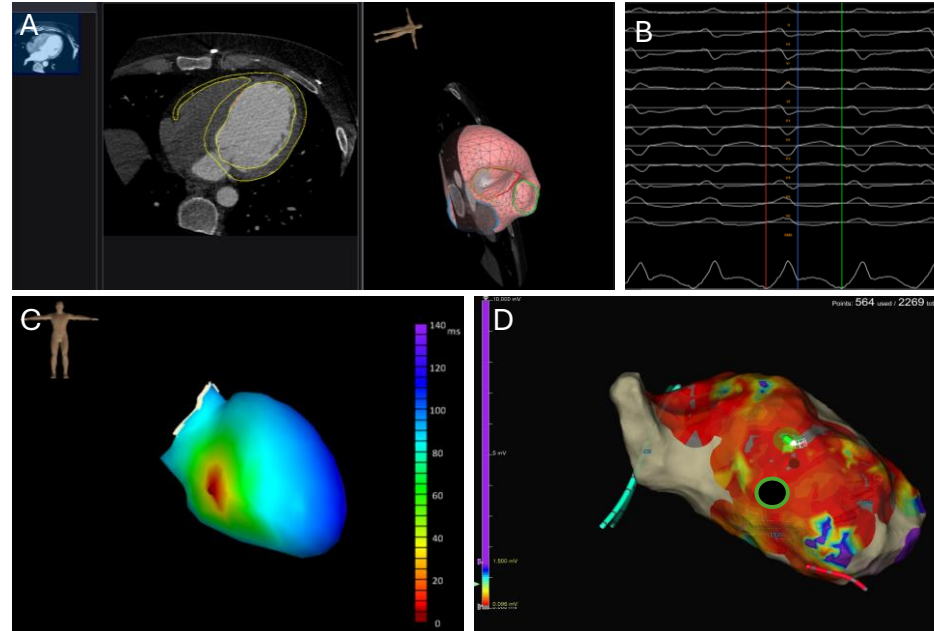
View in ventricular onset (VIVO) is a non-invasive mapping system used for localising the site of earliest activation in ventricular arrhythmia, utilising a mathematical algorithm, patient specific cardiac model (constructed using cross-sectional imaging data), 3D images of the patient's torso and a 12-lead electrocardiogram (ECG). Several publications have examined its role in the localisation of premature ventricular contractions (PVCs), and a 5 patient case series assessed its role in scar related re-entrant VT. However, its validity in a larger cohort and of the relationship to the relevant myocardial scar has not been investigated.

## Purpose

Assess the accuracy of the VIVO mapping system in localising the VT-SoO for patients with scar related re-entrant VT and its relationship to the relevant myocardial scar on cross-sectional imaging.

## Methods

**20 patients** with structural heart disease (18 ischaemic cardiomyopathy (ICM), 1 dilated cardiomyopathy (DCM), 1 hypertrophic cardiomyopathy (HCM)) (Male n=18, 63±14 years) and recent cross-sectional cardiac imaging, were recruited over a 16-month period. All patients had a clinical indication for VT ablation and were on optimal medical therapy. Invasive electro-anatomical mapping (EAM) was performed with the Advisor HD Grid multipolar catheter and maps were generated using Omnipolar electrograms (EGMs). The VT-SoO was identified using an activation- or pace-map by an experienced operator and the location defined using the American heart association's 17 segment model of the left ventricle during the procedure. VIVO maps were reviewed by a second independent operator and a segment allocated, scar segments were obtained from cross-sectional imaging. A "complete match" was defined as exact segment concordance between allocated segments, "partial match" as adjacent segments, and "no match" if it does not satisfy either of those requirements.

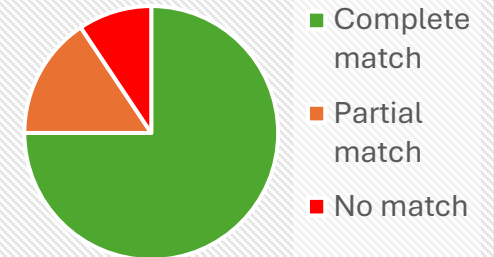


**Figure 1:** example case showing the imported cardiac CT scan as seen on VIVO (panel A); ECG tracing with the onset and offset of the QRS annotated (panel B); the VT-SoO as seen on VIVO based on the ECG, image of torso and cross-sectional imaging (panel C); and the VT-SoO based on EAM (PACE) mapping (panel D).

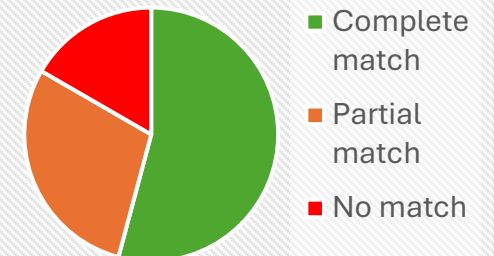
## Results

Mean left ventricular ejection fraction was  $35.5 \pm 10.6\%$ . Mean procedure time was  $242 \pm 70$  minutes, with a mean ablation time of  $20 \pm 11.1$  minutes. A total of 32 re-entrant VTs were mapped. The VT exit site was identified in all cases (11 activation-map; 21 pace-map). **A complete match between the EAM and VIVO map was seen in 75% of VTs and partial match in a further 15%. The VT-SoO was located within the myocardial scar (or directly adjacent to it) in 83% of accurately mapped VTs.** Procedural success was seen in 90% of patients at mean follow up of  $7.3 \pm 4.7$  months.

## VIVO and EAM correlation



## VIVO and scar correlation



## Conclusion

VIVO non-invasive mapping system was able to **accurately map the VT-SoO in scar dependent VT, and identify the relevant myocardial scar** as seen on cross-sectional imaging. Further research assessing its ability to accurately identify relevant ablation targets is ongoing.